(1)
$$(x+\delta x) \cdot x^{-1} = U_{p}^{a}(x) \delta x^{p}$$

 $(\psi + \delta +) \psi^{-1} = U_{p}^{a}(+) \delta \psi^{p}$
 $(x+\delta x) \cdot \psi \cdot (x \cdot y)^{-1} = (x+\delta x) \cdot x^{-1} = U_{a}^{\beta}(x) \delta x^{p}$
 $\Rightarrow U_{r}^{a}(\psi) / \delta \psi^{p} = U_{p}^{a}(x) \delta x^{p}$
 $\Rightarrow U_{r}^{a}(\psi) / \delta \psi^{p} = U_{p}^{a}(x) \delta x^{p}$
 $\Rightarrow V_{r}^{a}(\psi) \cdot \frac{\partial \psi^{r}}{\partial x^{p}} = V_{p}^{a}(x)$ ($\Rightarrow \frac{\partial \psi^{r}}{\partial x^{p}} = u_{a}^{r}(\psi) U_{p}^{a}(x)$
This is how to drive (PDE-1) in the lest betwee via

the infinitesimal notations.

(2) Lie Subgroups & Subalgebra.
Defea HCG is a Lie subgroup. if the inclusion
(1) It is a Subgroup & 2: H \to G is a smooth
immersion.
2b.
$$\eta \subset \sigma_{j}$$
 is a Subalgebra if it is a Subspace
& closed under [,]
Remark: (i) [x, y] is NOT associative
(i, i] = [-k, i] = -3
[j, [i, i]] = [-k, i] = -3
[j, [i]] = [-k, i] = -3
[j, [i]] = [-k, i] = -3
[j, [i]] = [-k, i] = -3
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[j, [i]] = [-k, i] = -3
[j, [i]] = [-k, i] = -3
[j

Ex.
is Not a regular embodding.
is Not regular embodding.
is Not regular embodding.
is Not regular embodding.
The reason his due to frobenius theorem:
terget vectors
let
$$d = |occll_1 \text{ Spr} \{X_{(0)}, \dots, X_{k}(x)\}, \{X_i\}|_{inverly} \forall x \in \mathbb{N}$$

independent & smooth, a k-dim distribution finct that
it is closed u.r.t [,]. Namely $\forall X_i \in D$.
 $[X, Y] \in D$.
then $\exists !a$ maximum integral "manifold Néfolimousian k) pessing
any given point $P \in M$. & $\forall x \in \mathbb{N}$ "The solution that has a some
any given point $P \in M$. & $\forall x \in \mathbb{N}$ "Freehing the by some
theorem 1: $\exists : I = 1$ (arrespondence between $\Im \subset Q$.
 $free subsights.$
 $free (H) denote the Lie algebra of H.
2: H (S G
(2) v Lie(H) (Si (G)) is a Lie algebra homeomorphism.$

In general.
$$\varphi: H \rightarrow G \implies \varphi : Y \rightarrow G \subseteq G$$

Shouth \mathcal{L} (Fi. x_{1}) = $[\varphi(x), \varphi(x)]$
 $f_{x}: T \rightarrow g$
 $P_{x}: T \rightarrow g$
 $P_{x}:$

Conversely, given
$$\gamma \in Q_{3}$$
 is subalgebre.
Which we may view as a subserve of Te 4: &
if extends the G by the left translation independent
 $X_{i}(q) = (l_{q})_{*}(x_{i})$
Namely γ is the speckent spece $S \text{ periods} X_{1} - X_{i}$?
Moreover γ is a subalgebre means
 $[X_{i}, X_{j}] \in \gamma$.
Now $\mathcal{A}_{i}^{i} = Specifix_{i}(s_{i}), \dots, X_{i}(s_{i})$?
is a distribution, smooths depends on γ
 $\forall X_{i} = \sum_{i=1}^{k} a_{i}(s_{i}) X_{i}(s_{i}), \quad Y = \sum_{i=1}^{k} b_{i}(s_{i}) X_{i}(s_{i})$
 $= [X_{i}, Y_{i}] = \sum_{i=1}^{k} a_{i}(s_{i}) b_{j}(s_{i}) [X_{i}, X_{j}]$
 $+ \sum_{i=1}^{k} a_{i}(s_{i}) b_{j}(s_{i}) [X_{i}, X_{j}]$
 $\Rightarrow [X_{i}, Y_{i}] \in \mathcal{A}_{i}.$ Since $[X_{i}, X_{j}]_{ij} \in \mathcal{A}_{i}(s_{i})$
 $\Rightarrow [X_{i}, Y_{i}] \in \mathcal{A}_{i}.$ Since $[X_{i}, X_{j}]_{ij} \in \mathcal{A}_{i}(s_{i})$.
 $\Rightarrow [X_{i}, Y_{i}] \in \mathcal{A}_{i}.$ Since $[X_{i}, X_{j}]_{ij} \in \mathcal{A}_{i}(s_{i})$.
 $\Rightarrow due to the assumption of the the maximum integration inflict pressing $e \in G$.$

Since
$$L_{g}H$$
 will be the interation of 10 prising g
Since Q is L_{g} invariant.
 $\Rightarrow V h \in H$ $h^{-1}H - Passing \in$
 $g H - passing \in$
 $\Rightarrow H = h^{-1}H$ $\forall h \in H$
 $\Rightarrow H = h^{-1}H$ $\forall h \in H$
 $\Rightarrow H = h^{-1}H$ $\forall h \in H$
 $\Rightarrow H = \int_{h \in H} h^{-1}H \Rightarrow H^{-1}H = H$
We can dude that H is closed under g-inversion
 $g - multiplication$
 $h_{1} \cdot h_{2} = h_{1} \cdot (h_{1})^{-1} = h_{1} \cdot (h_{2})^{-1} \in H$
Nemely, the integration submanifold H is a group.
 $VacXimum$
 $(locel, subtria groups)$ Establish the identification as two
connected in $g : Can the "morphisms" be
identified in $g : Can the "morphisms" be
identified in $g : G = R$
 $g : g : R : M \in I \to C$
But $\phi_{2} \in G_{1} \to G_{2}$ must be $g = h = h$.$$

Imposition If G₁ is connected,
$$\phi: G_1 \rightarrow G_1$$

is decided by $(\phi)_x \cdot g_1 \rightarrow g_1$
W. L. G We may also assume G₂ is connected since
 $\phi(G_1) \subset (G_2)_0 - He component containing e.$
Greph(ϕ) $\subset G_1 \times G_2$ is a Lie subgroup.
Site $(g_1, \phi(s_1)) \cdot (g_2, \phi(g_2)) = (s, s_1, \phi(g_1, s_2))$
 $= (g_1g_1, \phi(g_1), \phi(g_2)) = (s, s_1, \phi(g_1, s_2))$
 $\subset (f_1g_1, \phi(g_1), \phi(g_2)) = (s, s_1, \phi(g_1, s_2))$
 $\subset (f_1g_1, \phi(g_1), \phi(g_2)) = (s_1g_1, \phi(g_1, s_2))$
 $\subset (f_1g_1, \phi(g_1), \phi(g_2)) = (s_1g_1, \phi(g_1, s_2))$
 $\subset (f_1g_1, \phi(g_1), \phi(g_2)) = (s_1g_1, \phi(g_1, s_2))$
 $\subset (f_1g_1, \phi(g_1)) = G_1(g_1, \phi(g_1, s_2))$
 $\subseteq G_1(g_1, \phi(g_1)) = G_1(g_1, \phi(g_1, s_2))$
 $f_1(g_1) = (exp(f_1X), \phi(exp(f_1X))) = (exp(f_2X), exp(f_1g_1(s_1)))$
is the all possible 1-peremeter subgroups passing (e, e)
 $-\frac{d(G_1f_2)}{df_1}\Big|_{f=0} = (X, \phi_1(x)) \in g_1 \times g_1$
Since Lie (Grequely) decides Greph(ϕ)
 $\Rightarrow d_X$ uniquely decides ϕ .
Neuels, $\phi \rightarrow \phi_X$ is a 1-1 mep. if G₁ is connected
 $G_1 \rightarrow g_1$

Applications. Where
$$G = G_{h}: G \rightarrow G$$
 is
defined by $g \rightarrow hgh^{-1}$
(inspired weights action)
 $dG_{h} = (A_{1})_{a}, \ \mathcal{Q} \rightarrow \mathcal{G}$ is
a linear map which is also a Lie algebra homomorphic
hencely, $Ad_{i}: \ \mathcal{Q} \rightarrow \mathcal{G}$
This provides 1st approximation of the group structure.
 $Ad_{i}: \ \mathcal{Q} \rightarrow \mathcal{G}$
 $Ad_{i}: \ \mathcal{Q} \rightarrow \mathcal{G}(h, \mathcal{G})$
 $is a Lie algebra homomorphism
 $(Ae_{i}) = [ad_{i}, ad_{i}]$
 $\mathcal{Q} \rightarrow \mathcal{Q} = \mathcal{Q}(h, \mathcal{G})$
Hence study of Lie Group (Loonested) can be reduced to
 $2nd$ appreximation.
Study the map: ad: $g \rightarrow \mathcal{Q}(h, \mathcal{G})$
This is the adjust representation of the Lie algebra.
 $(A = Existent + \mathcal{G})$ such that $\mathcal{G} = the given one$
 $\exists a local Lie Group G, such that $\mathcal{G} = the given one$$$

$$\begin{array}{c} \text{A theorem of} \\ \text{Globelly, } & \text{HAdo. } & \text{H3 Lie algebra} \\ \text{Globelly, } & \text{HAdo. } & \text{H3 Lie algebra} \\ \text{Globelly, } & \text{HAdo. } & \text{H3 Lie algebra} \\ \text{Globelly, } & \text{HAdo. } & \text{H3 Lie algebra} \\ \text{Globelly, } & \text{H3 Lie algebra} \\ \text{Globelly, } & \text{H3 Lie algebra} \\ \text{H3 is a Sub-Lie algebra of } & \text{Gl(N, V)} \\ \ \text{H3 is a Sub-Lie algebra of } & \text{Gl(N, V)} \\ \ \text{H3 is a Sub-Lie algebra of } & \text{Gl(N, V)} \\ \ \text{H3 is a Sub-Lie algebra of } & \text{H3 is a Sub-Lie algebra of } \\ \ \text{H3 is a Sub-Lie algebra of } & \text{H3 is a Sub-Lie algebra of } \\ \ \text{H3 is a Sub-Lie algebra of } & \text{H3 is a Sub-Lie algebra of }$$

Lie
$$(G) = q$$

Namely: $\forall g: q, \rightarrow g_{\perp}$
Thm²: $\exists q: G_1 \rightarrow G_2$ such that $q_* = p$ if $\pi_*(G_1) = \{o\}$.
(5) To have the existence of q given $q_*: g_1 \rightarrow g_{\perp}$
 $G_1 \rightarrow G_2$

We need to assume G, is simply-connected.

Namely:
$$G_1, \dots, G_n$$
 For \dots
 exp for p become p
 exp for p become p
 $we need to assume for T_eG_1 $T_h(G_h) = \{o\}$.
 $g_1^{1/2}$ $g_2$$

The idea is to use the graph as before. $\begin{bmatrix} (x_1, x_1), (y_1, y_2) \end{bmatrix} = ([x_1, y_1], (x_1, y_1]) \\ \begin{bmatrix} (x_1, y_2, x_1), (y_1, y_2) \end{bmatrix} = ([x_1, x_1], [x_1, y_2], (x_2, y_2, y_2)] \\ \begin{bmatrix} (x_1, y_2, y_2, y_2, y_3, y_4) \end{bmatrix} = ([x_1, x_1], [x_2, y_3, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_3, y_4, y_4) \end{bmatrix} = ([x_1, x_1], [x_2, y_3, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4) \end{bmatrix} = ([x_1, x_1], [x_2, y_3, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4) \end{bmatrix} = ([x_1, x_1], [x_2, y_3, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4, y_4) \end{bmatrix} = ([x_1, x_1], [x_2, y_3, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4, y_4] \end{bmatrix} = ([x_1, x_1], [x_2, y_3, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4, y_4] \end{bmatrix} = ([x_1, x_1], [x_2, y_3, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, x_1], [x_2, y_3, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, x_1], [x_2, y_3, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, x_1], [x_2, y_3, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, x_1], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, x_1], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, x_1], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, x_1], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, x_1], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_4], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_2], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_4], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4, y_4] \end{bmatrix} = ([x_1, y_4], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4] \end{bmatrix} = ([x_1, y_4], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_2, y_4] \end{bmatrix} = ([x_1, y_4], [x_2, y_4]) \\ \begin{bmatrix} (x_1, y_4, y_4]$

Now: Let
$$R_{1}: G_{1} \times f_{2} \rightarrow G_{1}$$
 is the projection

$$(R)_{x} = Q_{1} \times f_{2} \rightarrow Q_{1}$$

$$(R)_{x} = G_{1} \times f_{2} \rightarrow G_{2} \qquad is culled a covering$$

$$(Q)_{x} = G_{1} \rightarrow G_{1} \qquad is g f_{x} = G_{1} \rightarrow G_{1}$$

$$(G)_{x} = G_{1} \rightarrow G_{1} \qquad is g (covering mep)$$

$$Row = hey T_{1}(G_{1}) = \int g_{1} \rightarrow H_{1} \qquad compartise f_{1} = G_{1} \rightarrow G_{2}$$

$$Row = hey T_{1}(G_{1}) = \int g_{1} \rightarrow H_{2} \qquad (p)_{x} (x, g(n)) \rightarrow x$$

$$The = P_{1}^{-1}: G_{1} \rightarrow H_{2} \qquad (compartise f_{1}: G_{1} \rightarrow G_{2})$$

$$P_{1}: H \rightarrow G_{1} \qquad is an isomorphism \qquad (p)_{x} (x, g(n)) \rightarrow x$$

$$The = P_{1}^{-1}: G_{1} \rightarrow H_{2} \qquad (compartise f_{2}: G_{1} \rightarrow G_{2})$$

$$P_{2}: H \rightarrow G_{2}$$

$$P_{2}: H \rightarrow G_{3} \qquad (op)_{x} (x) = \int (x) h_{y} \text{ the (costruction 1)}$$

$$G = Covering homomorphisms$$

$$Here we prove the claim: \quad \phi: G_{1} \rightarrow G_{2} \text{ is a covering}$$

$$if = \phi_{x}: g_{1} \rightarrow g_{2} \qquad is an isomorphism.$$

$$Lemma 1: \quad \Gamma = here f_{2} is a normal substrangles f_{3}$$

$$\psi(g(T_{3}) = f_{3}) \stackrel{i}{=} e$$

$$V \in G = \frac{f(x) + f_{3}}{f_{3}} = \frac{f(x) - f_{3}}{$$

$$\begin{array}{c} \begin{array}{c} \label{eq:second} \label{eq:second} \begin{split} & \begin{array}{c} \label{eq:second} \label{eq:second} \label{eq:second} \\ \label{eq:second} \\ & \begin{array}{c} \label{eq:second} \label{eq:second} \label{eq:second} \\ \end{array} \\ & \begin{array}{c} \label{eq:second} \label{eq:second} \label{eq:second} \\ \end{array} \\ & \begin{array}{c} \label{eq:second} \label{eq:second} \label{eq:second} \\ \end{array} \\ \end{array} \\ & \begin{array}{c} \label{eq:second} \label{eq:second} \label{eq:second} \label{eq:second} \\ \end{array} \\ \end{array} \\ & \begin{array}{c} \label{eq:second} \label{eq:$$

$$\begin{array}{c} \underline{PS} & \underline{O} & \underline{G}/f \text{ is a grap} \\ \hline \hline \hline \hline Pick, Uk V \text{ as chore } \Rightarrow & T & \underline{U} = \{e\} \\ \hline \hline \hline \hline \hline \hline Pick, Uk V \text{ as chore } \Rightarrow & T & \underline{U} = \{e\} \\ \hline \hline \hline \hline \hline \hline Pick, Uk V \text{ as chore } fe], & & & & \\ \hline \hline \hline \hline \hline \hline N_{GU} & Ue show the t \\ \hline \hline \hline \hline \hline \hline V & \underline{g} \in G & \exists g \in V & such that \left\{ \begin{array}{c} & & & \\ & & & \\ \hline &$$

$$\Rightarrow Y_{3}, v_{1} = \delta_{3} \delta_{2} k \Rightarrow (y_{1}^{V}, g_{1}, v_{1} = g_{1}^{V}, w_{2}^{V}) \in V_{2}v_{1}^{V} \in U$$

$$\Rightarrow A \quad contradiction \quad \int g_{2}^{V} \int \delta_{1}^{V}$$

$$\Rightarrow G/T \quad is \quad thandouff \quad & it \quad admits a maniful structure.$$

$$\Rightarrow G/T \quad is \quad thandouff \quad & it \quad admits a maniful structure.$$

$$\Rightarrow G/T \quad is \quad thandouff \quad & it \quad admits a maniful structure.$$

$$\Rightarrow G/T \quad is \quad theorem \quad & Group \; structure \; on \; a$$

$$= Coveries$$

$$\Rightarrow Coveries$$

$$= Coveries$$